



variable speed drive ATV12 - 0.75kW - 1hp - 200..240V - 3ph - with heat sink

ATV12H075M3

Main

| Range of product | Altivar 12 |
|------------------------------|----------------------|
| Product or component type | Variable speed drive |
| Product specific application | Simple machine |
| Mounting mode | Cabinet mount |
| Communication port protocol | Modbus |
| Supply frequency | 50/60 Hz +/- 5 % |
| [Us] rated supply voltage | 200240 V - 1510 % |
| Nominal output current | 4.2 A |
| Motor power hp | 1 hp |
| Motor power kW | 0.75 kW |
| | 1 hp |
| EMC filter | Without EMC filter |
| IP degree of protection | IP20 |

Complementary

| • | |
|------------------------------|---|
| Discrete input number | 4 |
| Discrete output number | 2 |
| Analogue input number | 1 |
| Analogue output number | 1 |
| Relay output number | 1 |
| Physical interface | 2-wire RS 485 |
| Connector type | 1 RJ45 |
| Continuous output current | 4.2 A at 4 kHz |
| Method of access | Server Modbus serial |
| Speed drive output frequency | 0.5400 Hz |
| Speed range | 120 |
| Sampling duration | 20 ms, tolerance +/- 1 ms for logic input 10 ms for analogue input |
| Linearity error | +/- 0.3 % of maximum value for analogue input |
| Frequency resolution | Analog input: converter A/D, 10 bits |

| Time constant | 20 ms +/- 1 ms for reference change |
|--|--|
| Transmission rate | 9.6 kbit/s |
| Transmission rate | 19.2 kbit/s 38.4 kbit/s |
| Transmission frame | RTU |
| Number of addresses | 1247 |
| Data format | 8 bits, configurable odd, even or no parity |
| Communication service | Read holding registers (03) 29 words Write single register (06) 29 words Write multiple registers (16) 27 words Read/write multiple registers (23) 4/4 words Read device identification (43) |
| Type of polarization | No impedance |
| 4 quadrant operation possible | False |
| Asynchronous motor control profile | Sensorless flux vector control Voltage/frequency ratio (V/f) Quadratic voltage/frequency ratio |
| Maximum output frequency | 4 kHz |
| Transient overtorque | 150170 % of nominal motor torque depending on drive rating and type of motor |
| Acceleration and deceleration ramps | Linear from 0 to 999.9 s S U |
| Motor slip compensation | Preset in factory Adjustable |
| Switching frequency | 216 kHz adjustable 416 kHz with derating factor |
| Nominal switching frequency | 4 kHz |
| Braking to standstill | By DC injection |
| Brake chopper integrated | False |
| Line current | 6.3 A at 100 V (heavy duty) 5.3 A at 120 V (heavy duty) |
| Maximum input current | 5.3 A |
| Maximum output voltage | 240 V |
| Apparent power | 2.2 kVA at 240 V (heavy duty) |
| Maximum transient current | 6.3 A during 60 s (heavy duty) 6.9 A during 2 s (heavy duty) |
| Network frequency | 5060 Hz |
| Relative symmetric network frequency tolerance | 5 % |
| Prospective line Isc | 5 kA |
| Base load current at high overload | 4.2 A |
| Power dissipation in W | Natural: 41.0 W |
| With safety function Safely Limited Speed (SLS) | False |
| With safety function Safe brake management (SBC/SBT) | False |
| With safety function Safe Operating Stop (SOS) | False |
| With safety function Safe Position (SP) | False |
| With safety function Safe programmable logic | False |

| With safety function Safe Speed Monitor (SSM) | False |
|--|---|
| With safety function Safe Stop 1 (SS1) | False |
| With sft fct Safe Stop 2 (SS2) | False |
| With safety function Safe torque off (STO) | False |
| With safety function Safely Limited Position (SLP) | False |
| With safety function Safe Direction (SDI) | False |
| Protection type | Line supply overvoltage Line supply undervoltage Overcurrent between output phases and earth Overheating protection Short-circuit between motor phases Against input phase loss in three-phase Thermal motor protection via the drive by continuous calculation of I²t |
| Tightening torque | 0.8 N.m |
| Insulation | Electrical between power and control |
| Quantity per set | Set of 1 |
| Width | 72 mm |
| Height | 143 mm |
| Depth | 131.2 mm |
| Net weight | 0.8 kg |
| Environment | |
| Operating altitude | <= 1000 m without derating > 10003000 m with current derating 1 % per 100 m |
| Operating position | Vertical +/- 10 degree |
| Product certifications | NOM CSA C-Tick UL GOST RCM KC |
| Marking | CE |
| Standards | UL 508C UL 618000-5-1 EN/IEC 61800-5-1 EN/IEC 61800-3 |
| Assembly style | With heat sink |
| Electromagnetic compatibility | Electrical fast transient/burst immunity test level 4 conforming to EN/IEC 61000-4-4 Electrostatic discharge immunity test level 3 conforming to EN/IEC 61000-4-2 Immunity to conducted disturbances level 3 conforming to EN/IEC 61000-4-6 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to EN/IEC 61000-4-3 Surge immunity test level 3 conforming to EN/IEC 61000-4-5 Voltage dips and interruptions immunity test conforming to EN/IEC 61000-4-11 |
| Environmental class (during operation) | Class 3C3 according to IEC 60721-3-3 Class 3S2 according to IEC 60721-3-3 |
| Maximum acceleration under shock impact (during operation) | 150 m/s² at 11 ms |
| Maximum acceleration under vibrational stress (during operation) | 10 m/s² at 13200 Hz |
| Maximum deflection under vibratory load (during operation) | 1.5 mm at 213 Hz |
| Overvoltage category | Class III |
| | |

| Regulation loop | Adjustable PID regulator | |
|---------------------------------------|--|--|
| Electromagnetic emission | Radiated emissions environment 1 category C2 conforming to EN/IEC 61800-3 216 kHz shielded motor cable Conducted emissions with additional EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 412 kHz shielded motor cable <20 m Conducted emissions with additional EMC filter environment 2 category C3 conforming to EN/IEC 61800-3 412 kHz shielded motor cable <20 m | |
| Vibration resistance | 1 gn (f = 13200 Hz) conforming to EN/IEC 60068-2-6 1.5 mm peak to peak (f = 313 Hz) - drive unmounted on symmetrical DIN rail - conforming to EN/IE 60068-2-6 | |
| Shock resistance | 15 gn conforming to EN/IEC 60068-2-27 for 11 ms | |
| Relative humidity | 595 % without condensation conforming to IEC 60068-2-3 595 % without dripping water conforming to IEC 60068-2-3 | |
| Noise level | 0 dB | |
| Pollution degree | 2 | |
| Ambient air transport temperature | -2570 °C | |
| Ambient air temperature for operation | -1040 °C without derating 4060 °C with current derating 2.2 % per °C | |
| Ambient air temperature for storage | -2570 °C | |
| Packing Units | | |
| Unit Type of Package 1 | PCE | |
| Number of Units in Package 1 | 1 | |
| Package 1 Height | 12.000 cm | |
| Package 1 Width | 19.000 cm | |
| Package 1 Length | 19.000 cm | |
| Package 1 Weight | 1.054 kg | |
| Unit Type of Package 2 | P06 | |
| Number of Units in Package 2 | 45 | |
| Package 2 Height | 75.000 cm | |
| Package 2 Width | 60.000 cm | |
| Package 2 Length | 80.000 cm | |
| Package 2 Weight | 60.430 kg | |
| Offer Sustainability | | |
| Sustainable offer status | Green Premium product | |
| REACh Regulation | REACh Declaration | |
| EU RoHS Directive | Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration | |
| Mercury free | Yes | |
| China RoHS Regulation | China RoHS declaration | |
| RoHS exemption information | Yes | |
| Environmental Disclosure | Product Environmental Profile | |
| Circularity Profile | End of Life Information | |
| WEEE | | |

Contractual warranty

Warranty

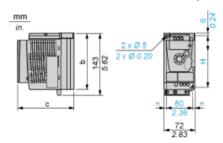
18 months

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Dimensions Drawings

Dimensions

Drive without EMC Conformity Kit



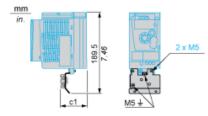
Dimensions in mm

| b | С | Н |
|-----|-------|-----|
| 130 | 131.2 | 120 |

Dimensions in in.

| b | С | Н |
|------|------|------|
| 5.12 | 5.16 | 4.72 |

Drive with EMC Conformity Kit



Dimensions in mm

| c1 | |
|----|--|
| 63 | |

Dimensions in in.

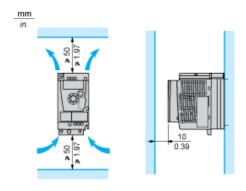
| c1 | |
|------|--|
| 2.48 | |

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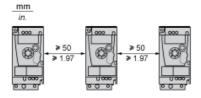
Mounting and Clearance

Mounting Recommendations

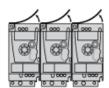
Clearance for Vertical Mounting



Mounting Type A

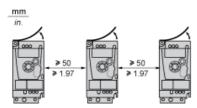


Mounting Type B



Remove the protective cover from the top of the drive.

Mounting Type C

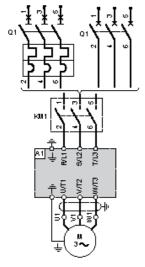


Remove the protective cover from the top of the drive.

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Connections and Schema

Three-Phase Power Supply Wiring Diagram



A1 KM1 Contactor (only if a control circuit is needed) Circuit breaker

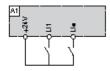
Q1

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Connections and Schema

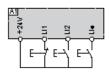
Recommended Schemes

2-Wire Control for Logic I/O with Internal Power Supply



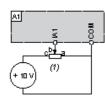
LI1: Forward LI•: Reverse **A1**: Drive

3-Wire Control for Logic I/O with Internal Power Supply



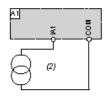
LI1: Stop LI2: Forward Reverse

Analog Input Configured for Voltage with Internal Power Supply



(1) A1 : 2.2 $k\Omega...10~k\Omega$ reference potentiometer

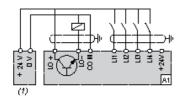
Analog Input Configured for Current with Internal Power Supply



0-20 mA 4-20 mA supply

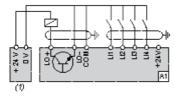
Drive

Connected as Positive Logic (Source) with External 24 vdc Supply



24 vdc supply

Connected as Negative Logic (Sink) with External 24 vdc supply

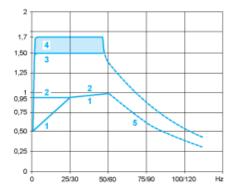


24 vdc supply

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Performance Curves

Torque Curves



- 1: Self-cooled motor: continuous useful torque (1)
- 2: Force-cooled motor: continuous useful torque
- 3: Transient overtorque for 60 s 4: Transient overtorque for 2 s
- 5: Torque in overspeed at constant power (2)
- For power ratings ≤ 250 W, derating is 20% instead of 50% at very low frequencies.
- (1) (2) The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of the

Recommended replacement(s)