Product datasheet

Specifications

variable speed drive ATV12 - 0.18kW - 0.25hp - 200..240V - 1ph

ATV12H018M2

Main

Range of product	Altivar 12
Product or component type	Variable speed drive
Product specific application	Simple machine
Mounting mode	Cabinet mount
Communication port protocol	Modbus
Supply frequency	50/60 Hz +/- 5 %
[Us] rated supply voltage	200...240 V - 15...10 %
Nominal output current	1.4 A
Motor power hp	0.25 hp
Motor power kW	0.18 kW 0.25 hp
EMC filter	Integrated
IP degree of protection	IP20

Complementary

Discrete input number	4
Discrete output number	2
Analogue input number	1
Analogue output number	1
Relay output number	1
Physical interface	2-wire RS 485
Connector type	1 RJ45
Continuous output current	1.4 A at 4 kHz
Method of access	Server Modbus serial
Speed drive output frequency	0.5…400 Hz
Speed range	1…20
Sampling duration	20 ms, tolerance +/- 1 ms for logic input 10 ms for analogue input
Linearity error	+/- 0.3 % of maximum value for analogue input
Frequency resolution	Analog input: converter A/D, 10 bits

	Display unit: 0.1 Hz
Time constant	20 ms +/- 1 ms for reference change
Transmission rate	9.6 kbit/s 19.2 kbit/s 38.4 kbit/s
Transmission frame	RTU
Number of addresses	1…247
Data format	8 bits, configurable odd, even or no parity
Communication service	Read holding registers (03) 29 words Write single register (06) 29 words Write multiple registers (16) 27 words Read/write multiple registers (23) 4/4 words Read device identification (43)
Type of polarization	No impedance
4 quadrant operation possible	False
Asynchronous motor control profile	Voltage/frequency ratio (V/f) Sensorless flux vector control Quadratic voltage/frequency ratio
Maximum output frequency	4 kHz
Transient overtorque	150…170 % of nominal motor torque depending on drive rating and type of motor
Acceleration and deceleration ramps	U Linear from 0 to 999.9 s S
Motor slip compensation	Preset in factory Adjustable
Switching frequency	2...16 kHz adjustable 4...16 kHz with derating factor
Nominal switching frequency	4 kHz
Braking to standstill	By DC injection
Brake chopper integrated	False
Line current	3.4 A at 100 V (heavy duty) 2.8 A at 120 V (heavy duty)
Maximum input current	2.8 A
Maximum output voltage	240 V
Apparent power	0.7 kVA at 240 V (heavy duty)
Maximum transient current	2.1 A during 60 s (heavy duty) 2.3 A during 2 s (heavy duty)
Network frequency	50...60 Hz
Relative symmetric network frequency tolerance	5 %
Prospective line Isc	1 kA
Base load current at high overload	1.4 A
Power dissipation in W	Natural: 18.0 W
With safety function Safely Limited Speed (SLS)	False
With safety function Safe brake management (SBC/SBT)	False
With safety function Safe Operating Stop (SOS)	False
With safety function Safe Position (SP)	False
With safety function Safe programmable logic	False

With safety function Safe Speed Monitor (SSM)	False
With safety function Safe Stop 1 (SS1)	False
With sft fct Safe Stop 2 (SS2)	False
With safety function Safe torque off (STO)	False
With safety function Safely Limited Position (SLP)	False
With safety function Safe Direction (SDI)	False
Protection type	Line supply overvoltage Line supply undervoltage Overcurrent between output phases and earth Overheating protection Short-circuit between motor phases Against input phase loss in three-phase Thermal motor protection via the drive by continuous calculation of I^2t
Tightening torque	0.8 N.m
Insulation	Electrical between power and control
Quantity per set	Set of 1
Width	72 mm
Height	143 mm
Depth	102.2 mm
Net weight	0.7 kg

Environment

Operating altitude	> 1000...2000 m with current derating 1 % per 100 m <= 1000 m without derating
Operating position	Vertical +/- 10 degree
Product certifications	NOM CSA C-Tick UL GOST RCM KC
Marking	CE
Standards	UL 508C UL 618000-5-1 EN/IEC 61800-5-1 EN/IEC 61800-3
Assembly style	On base plate
Electromagnetic compatibility	Electrical fast transient/burst immunity test level 4 conforming to EN/IEC 61000-4-4 Electrostatic discharge immunity test level 3 conforming to EN/IEC 61000-4-2 Immunity to conducted disturbances level 3 conforming to EN/IEC 61000-4-6 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to EN/IEC 61000-4-3 Surge immunity test level 3 conforming to EN/IEC 61000-4-5 Voltage dips and interruptions immunity test conforming to EN/IEC 61000-4-11
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S2 according to IEC 60721-3-3
Maximum acceleration under shock impact (during operation)	150 m/s^2 at 11 ms
Maximum acceleration under vibrational stress (during operation)	10 m/s^2 at 13...200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 2...13 Hz
Overvoltage category	Class III

Regulation loop	Adjustable PID regulator
Electromagnetic emission	Radiated emissions environment 1 category C2 conforming to EN/IEC 61800-3 2...16 kHz shielded motor cable Conducted emissions with integrated EMC filter environment 1 category C1 conforming to EN/IEC 61800-3 2, 4, 8, 12 and 16 kHz shielded motor cable <5 m Conducted emissions with integrated EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 2...12 kHz shielded motor cable <5 m Conducted emissions with integrated EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 2, 4 and 16 kHz shielded motor cable <10 m Conducted emissions with additional EMC filter environment 1 category C1 conforming to EN/IEC 61800-3 4...12 kHz shielded motor cable <20 m Conducted emissions with additional EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 4...12 kHz shielded motor cable <50 m Conducted emissions with additional EMC filter environment 2 category C3 conforming to EN/IEC 61800-3 4...12 kHz shielded motor cable <50 m
Vibration resistance	1 gn (f = 13…200 Hz) conforming to EN/IEC 60068-2-6 1.5 mm peak to peak (f = 3…13 Hz) - drive unmounted on symmetrical DIN rail - conforming to EN/IEC 60068-2-6
Shock resistance	15 gn conforming to EN/IEC 60068-2-27 for 11 ms
Relative humidity	5…95 % without condensation conforming to IEC 60068-2-3 5…95 % without dripping water conforming to IEC 60068-2-3
Noise level	0 dB
Pollution degree	2
Ambient air transport temperature	-25…70 °C
Ambient air temperature for operation	-10…40 °C without derating 40…60 °C with current derating 2.2 % per °C
Ambient air temperature for storage	-25…70 °C

Packing Units

Unit Type of Package 1	Db
Number of Units in Package 1	1
Package 1 Height	12.000 cm
Package 1 Width	18.600 cm
Package 1 Length	19.500 cm
Package 1 Weight	895 g
Unit Type of Package 2	P06
Number of Units in Package 2	45
Package 2 Height	75.000 cm
Package 2 Width	60.000 cm
Package 2 Length	80.000 cm
Package 2 Weight	52.780 kg

Offer Sustainability

Sustainable offer status	Green Premium product
REACh Regulation	REACh Declaration
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration
Mercury free	Yes
China RoHS Regulation	China RoHS declaration
RoHS exemption information	Yes
Environmental Disclosure	Product Environmental Profile
Circularity Profile	End of Life Information

WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

Contractual warranty

Warranty	18 months

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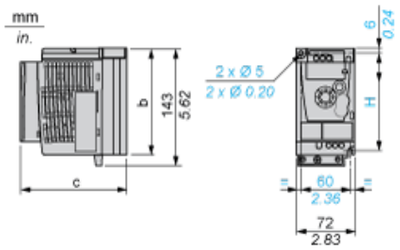
Dimensions Drawings

Dimensions

Drive without EMC Conformity Kit



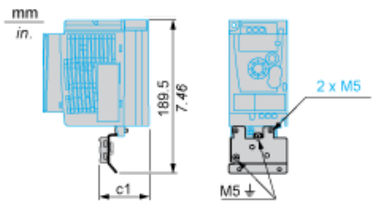
Dimensions in mm

b	c	H
142	102.2	131

Dimensions in in.

b	c	H
5.59	4.02	5.16

Drive with EMC Conformity Kit



Dimensions in mm

c1
34

Dimensions in in.

c1
1.34

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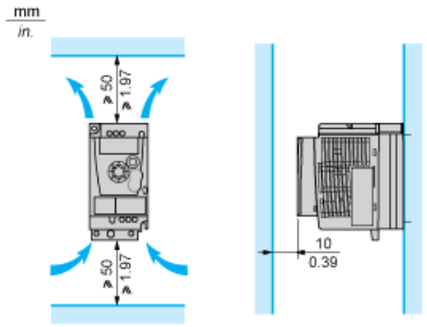
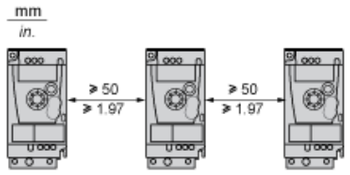
Mounting and Clearance

Mounting Recommendations

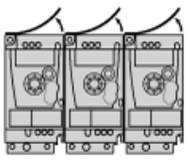
Clearance for Vertical Mounting



Mounting Type A

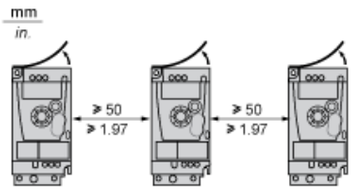


Mounting Type B



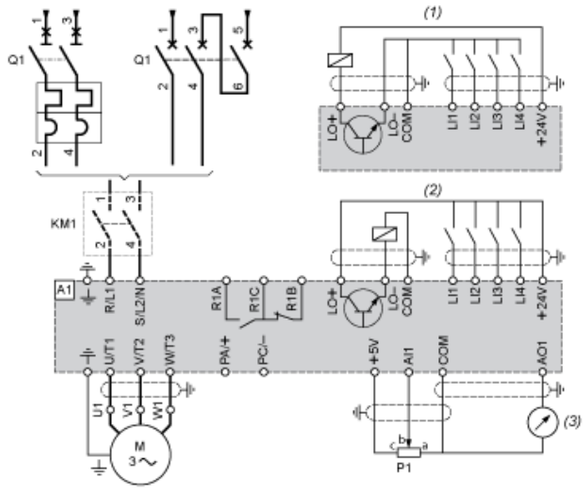
Remove the protective cover from the top of the drive.

Mounting Type C



Remove the protective cover from the top of the drive.

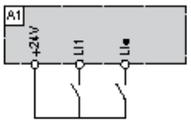
Single-Phase Power Supply Wiring Diagram



A1 Drive
KM1 Contactor (only if a control circuit is needed)
P1 2.2 kΩ reference potentiometer. This can be replaced by a 10 kΩ potentiometer (maximum).
Q1 Circuit breaker
(1) Negative logic (Sink)
(2) Positive logic (Source) (factory set configuration)
(3) 0...10 V or 0...20 mA

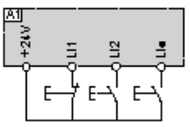
Recommended Schemes

2-Wire Control for Logic I/O with Internal Power Supply



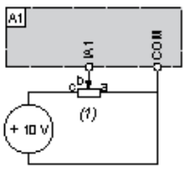
LI1 : Forward
LI• : Reverse
A1 : Drive

3-Wire Control for Logic I/O with Internal Power Supply



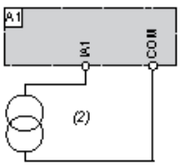
LI1 : Stop
LI2 : Forward
LI• : Reverse
A1 : Drive

Analog Input Configured for Voltage with Internal Power Supply



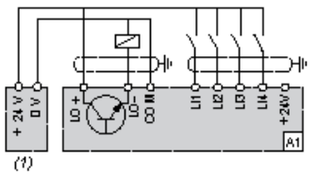
(1) 2.2 kΩ…10 kΩ reference potentiometer
A1 : Drive

Analog Input Configured for Current with Internal Power Supply



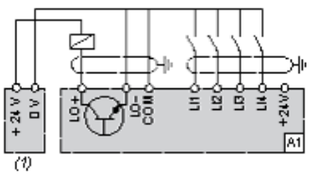
(2) 0-20 mA 4-20 mA supply
A1 : Drive

Connected as Positive Logic (Source) with External 24 vdc Supply



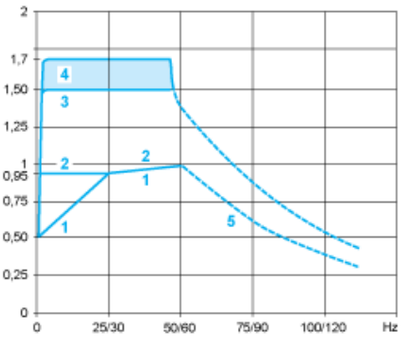
(1) 24 vdc supply
A1 : Drive

Connected as Negative Logic (Sink) with External 24 vdc supply



(1) 24 vdc supply
A1 : Drive

Torque Curves



1 : Self-cooled motor: continuous useful torque **(1)**
2 : Force-cooled motor: continuous useful torque
3 : Transient overtorque for 60 s
4 : Transient overtorque for 2 s
5 : Torque in overspeed at constant power **(2)**
(1) For power ratings ≤ 250 W, derating is 20% instead of 50% at very low frequencies.
(2) The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of th

Recommended replacement(s)